

12. Wilberforce Pendulum

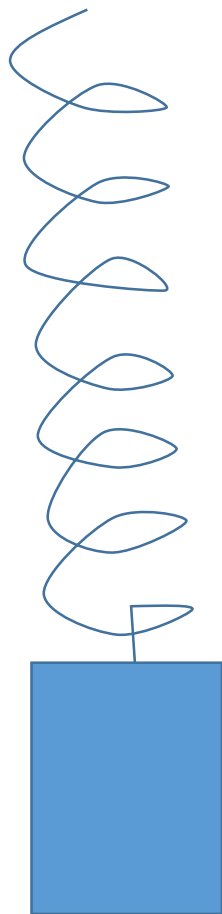
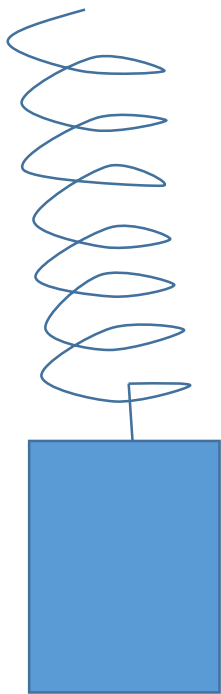
Sergej Faletič

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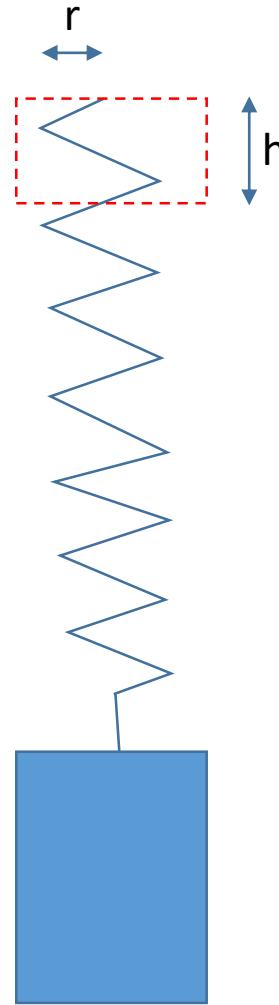
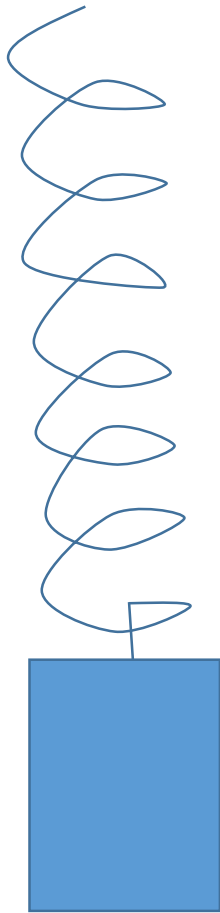
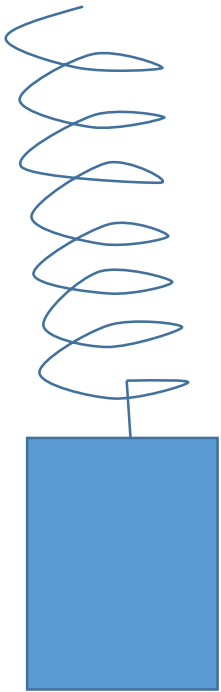
The phenomenon

- <https://www.youtube.com/watch?v=S42ILTlnfZc>

Qualitative explanation



Qualitative explanation

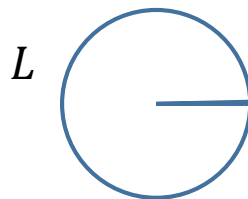


Length:

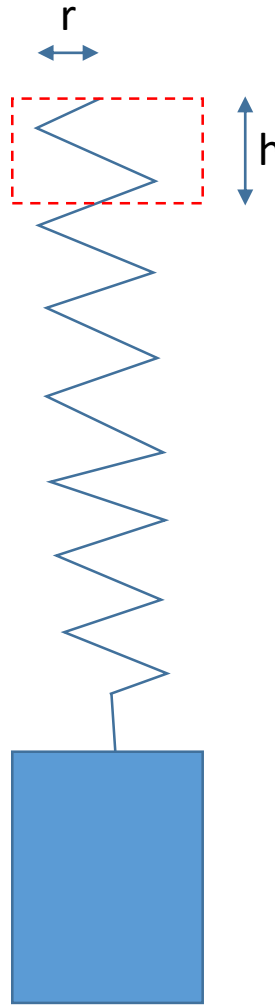
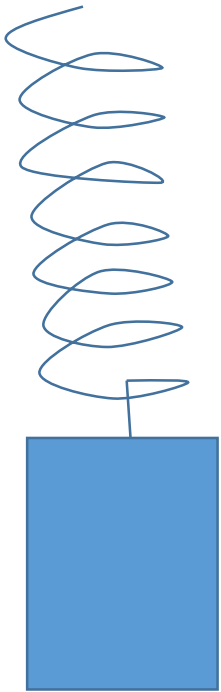
$$L = \sqrt{h^2 + (2\pi r)^2}$$

radius might change,
but let us ignore this
for now

$$r = r(h)$$



Qualitative explanation

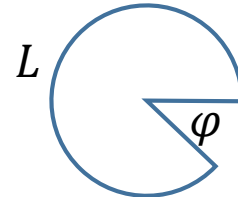
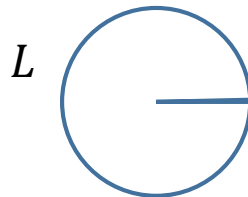


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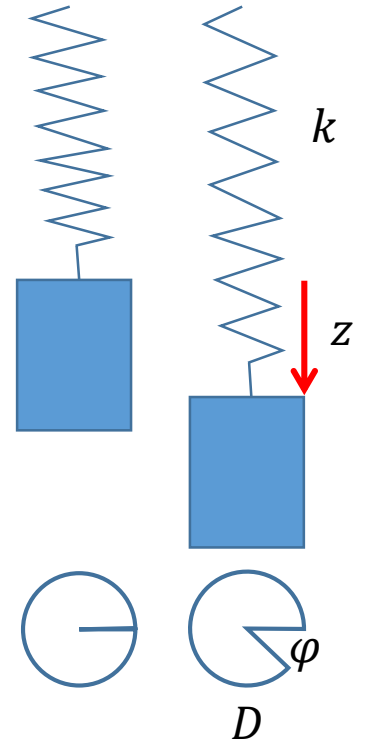
$$r = r(h)$$



Calculation

$$m \frac{d^2 z}{dt^2} = -kz$$

$$I \frac{d^2 \varphi}{dt^2} = -D\varphi$$



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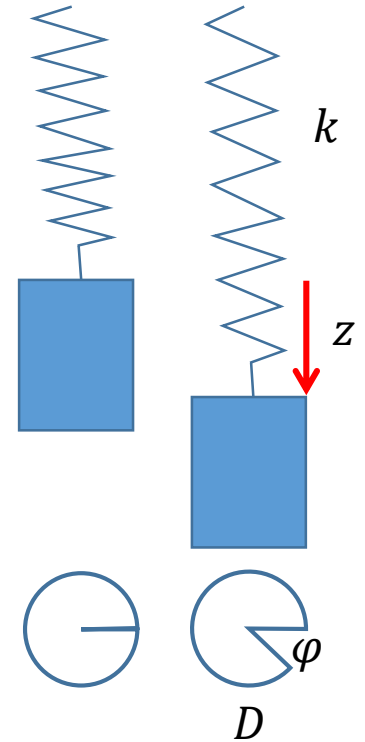
$$I \frac{d^2 \varphi}{dt^2} = -D\varphi$$

$$z(t) = A \cos(\omega_z t + \delta)$$

$$\varphi(t) = B \cos(\omega_\varphi t + \delta)$$

$$\omega_z = \sqrt{k/m}$$

$$\omega_\varphi = \sqrt{D/I}$$



Calculation

$$m \frac{d^2 z}{dt^2} = -kz - \xi \varphi$$

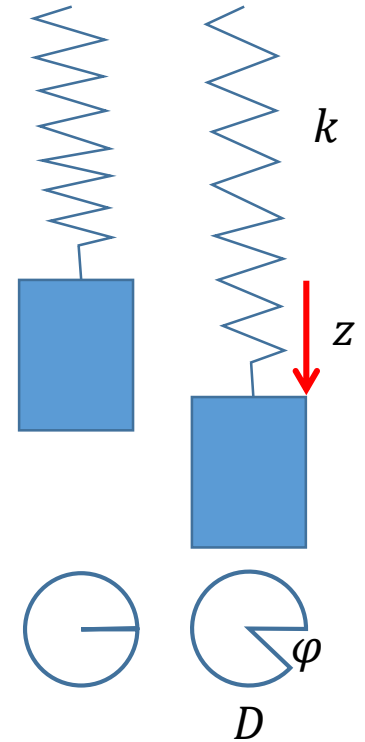
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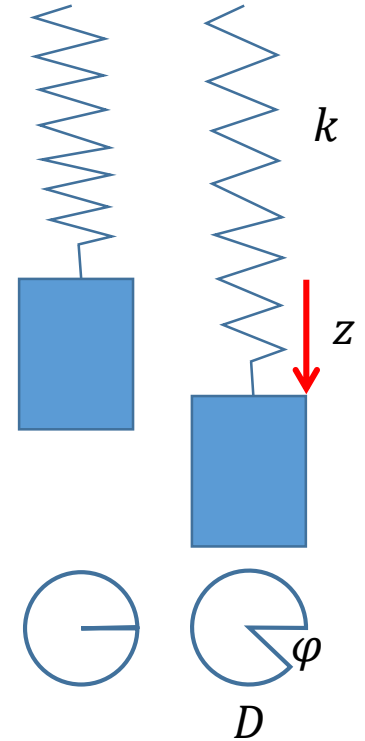
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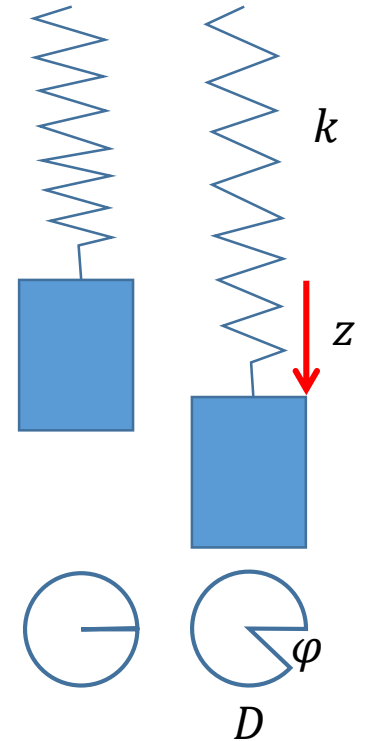
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$$\varphi(t) = B \cos(\omega t + \delta)$$

$$\omega_\varphi = \sqrt{D/I}$$

$$\omega_{\pm}^2 = \frac{1}{2} \left[\omega_z^2 + \omega_\varphi^2 \pm \sqrt{(\omega_z^2 - \omega_\varphi^2)^2 + \frac{4\xi}{mI}} \right]$$



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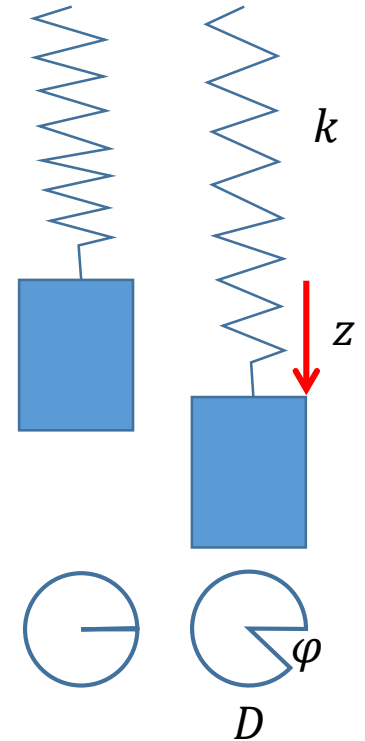
$$\varphi(t) = B \cos(\omega t + \delta)$$

$$\omega_\varphi = \sqrt{D/I}$$

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$$z(t) = A_+ \cos(\omega_+ t + \delta_+) + A_- \cos(\omega_- t + \delta_-),$$

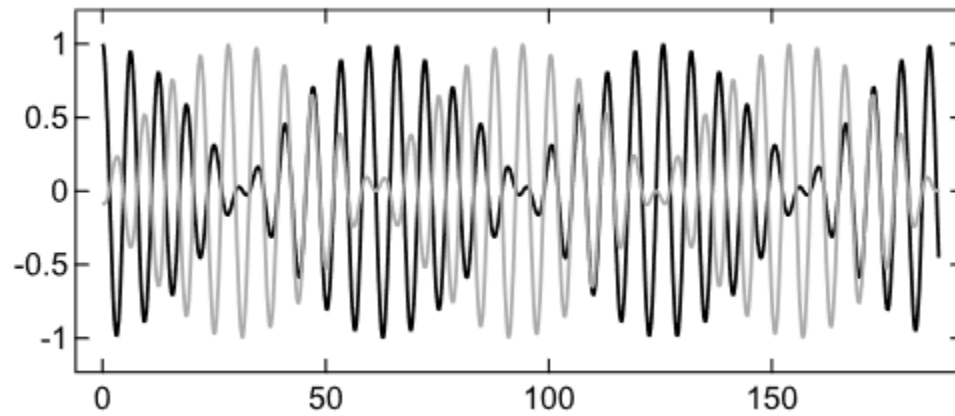
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Calculation results

$$z(t) = A_+ \cos(\omega_+ t + \delta_+) + A_- \cos(\omega_- t + \delta_-),$$

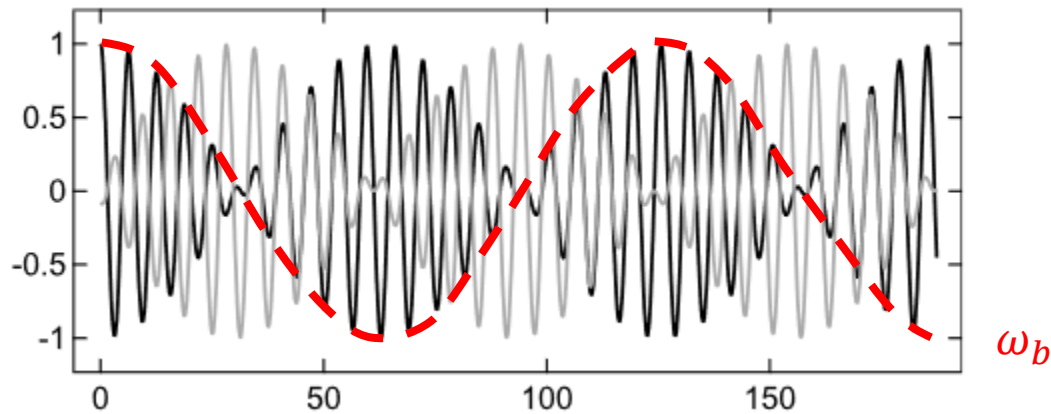
$$\varphi(t) = B_+ \cos(\omega_+ t + \delta_+) + B_- \cos(\omega_- t + \delta_-).$$



Calculation results

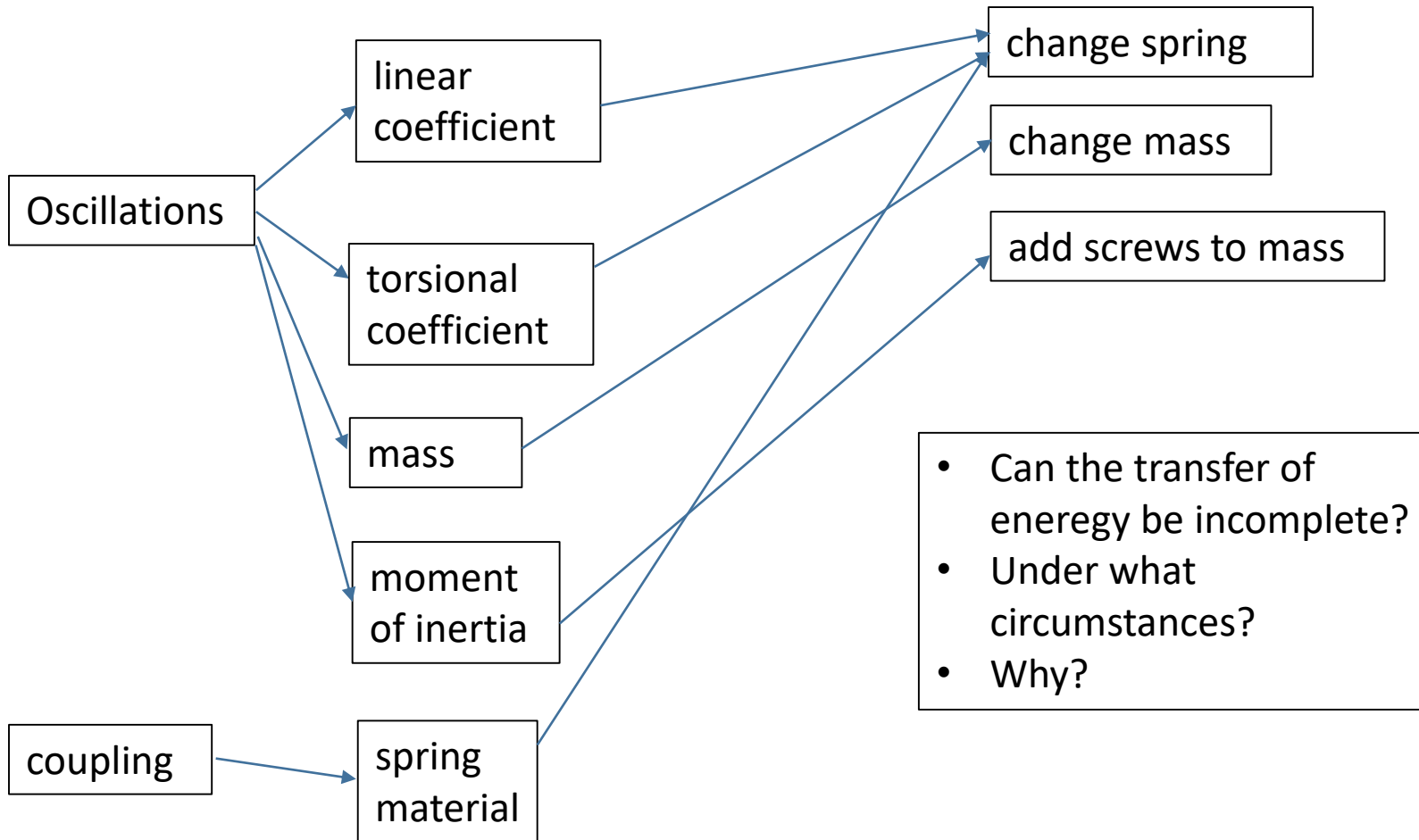
$$z(t) = A_+ \cos(\omega_+ t + \delta_+) + A_- \cos(\omega_- t + \delta_-),$$

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$$\omega_{\pm}^2 = \frac{1}{2} \left[\omega_z^2 + \omega_{\varphi}^2 \pm \sqrt{(\omega_z^2 - \omega_{\varphi}^2)^2 + \frac{4\xi}{mI}} \right]$$

Possible parameters to investigate



- Additions

B. The spiral spring

The spring of the Wilberforce pendulum must be adjusted to the mass and the rotational inertia of the pendulum bob. Assuming an ideal spring, i.e., a negligible mass and rotational inertia (*vide infra*), the angular frequencies of the translational and rotational oscillations are, respectively, $\omega_z = \sqrt{k/m}$ and $\omega_\varphi = \sqrt{\kappa/I}$. The spring and torsion constants are related to material properties via²³

$$k = \frac{1}{8} \cdot \frac{G}{D^3} \cdot \frac{d^4}{n}, \quad (9)$$

$$\kappa = \frac{1}{3670} \cdot \frac{E}{D} \cdot \frac{d^4}{n}, \quad (10)$$

(G : shear modulus, E : Young modulus, d : wire diameter, D : average coil diameter, n : number of windings), which yields

$$D = \sqrt{\frac{1835}{4} \cdot \frac{\kappa}{k} \cdot \frac{G}{E}}, \quad (11)$$